

Zero forcing: How to monitor an electricity network efficiently?

Jephian C.-H. Lin 林晉宏

Department of Applied Mathematics, National Sun Yat-sen University

March 22, 2022

Eindhoven SPOR Seminar, Eindhoven, The Netherlands

System of linear equations

$$\begin{array}{rclcrcl} 2x & +3y & -z & = & 4 \\ x & -y & +2z & = & 3 \\ -3x & +2y & +z & = & 2 \end{array}$$

Hard to know if the solution exists, or if the solution is unique.

I don't want to solve it!

System of linear equations

$$\begin{array}{rclcrcl} 2x & +3y & -z & = & 4 \\ x & -y & +2z & = & 3 \\ -3x & +2y & +z & = & 2 \end{array}$$

Hard to know if the solution exists, or if the solution is unique.

I don't want to solve it!

System of linear equations

$$\begin{array}{rclcrcl} 2x & +3y & -z & = & 4 \\ x & -y & +2z & = & 3 \\ -3x & +2y & +z & = & 2 \end{array}$$

Hard to know if the solution exists, or if the solution is unique.

I don't want to solve it!

System of linear equations

$$\begin{array}{rclcrcl} 2x & +y & -z & = & 1 \\ & 2y & & = & 4 \\ & +2y & +3z & = & 7 \end{array}$$

Easy to see $y = 2$, then $z = 1$, and then $x = 0$.
Easy to know the solution exists and is unique.

I like it! 😊

System of linear equations

$$\begin{array}{rclcrcl} 2x & +y & -z & = & 1 \\ & 2y & & = & 4 \\ & +2y & +3z & = & 7 \end{array}$$

Easy to see $y = 2$, then $z = 1$, and then $x = 0$.
Easy to know the solution exists and is unique.

I like it! 😊

System of linear equations

$$\begin{array}{rclcl} 2x & +y & -z & = & 1 \\ & 2y & & = & 4 \\ & +2y & +3z & = & 7 \end{array}$$

Easy to see $y = 2$, then $z = 1$, and then $x = 0$.
Easy to know the solution exists and is unique.

I like it! 😊

Main philosophy

$$2x + y + 3z = 7$$

$$x = 1, y = 2 \implies z = 1$$

In a linear equation, if all but one variable are known, then this remaining variable is also known.

$$2x + y + 3z = 0$$

$$x = 0, y = 0 \implies z = 0$$

In a homogeneous linear equation, if all but one variable are zero, then this remaining variable is also zero.

Hidden triangle in a system

$$\begin{array}{rclclcl} 1. & x & & +z & & +u & = & 0 \\ 2. & & y & +z & & & = & 0 \\ 3. & x & +y & +z & +w & +u & = & 0 \\ 4. & & & z & +w & & = & 0 \\ 5. & x & & +z & & +u & = & 0 \end{array}$$

Given information: $x = y = 0$. Then

$$2. \implies z = 0,$$

$$1. \implies u = 0,$$

$$3. \implies w = 0.$$

Hidden triangle in a system

$$\begin{array}{rclclcl} 1. & x & & +z & & +u & = & 0 \\ 2. & & y & +z & & & = & 0 \\ 3. & x & +y & +z & +w & +u & = & 0 \\ 4. & & & z & +w & & = & 0 \\ 5. & x & & +z & & +u & = & 0 \end{array}$$

Given information: $x = y = 0$. Then

$$2. \implies z = 0,$$

$$1. \implies u = 0,$$

$$3. \implies w = 0.$$

Hidden triangle in a system

$$\begin{array}{rclclcl} 1. & x & & +z & & +u & = 0 \\ 2. & & y & +z & & & = 0 \\ 3. & x & +y & +z & +w & +u & = 0 \\ 4. & & & z & +w & & = 0 \\ 5. & x & & +z & & +u & = 0 \end{array}$$

Given information: $x = y = 0$. Then

$$2. \implies z = 0,$$

$$1. \implies u = 0,$$

$$3. \implies w = 0.$$

Hidden triangle in a system

$$\begin{array}{rcccccc} 2. & & y & +z & & = 0 \\ 1. & x & & +z & +u & = 0 \\ 3. & x & +y & +z & +w & +u = 0 \\ 4. & & & z & +w & = 0 \\ 5. & x & & +z & & +u = 0 \end{array}$$

Given information: $x = y = 0$. Then

$$\begin{array}{l} 2. \implies z = 0, \\ 1. \implies u = 0, \\ 3. \implies w = 0. \end{array}$$

Hidden triangle in a system

$$\begin{array}{rclcl} 2. & & y & +z & = 0 \\ 1. & x & & +z & +u & = 0 \\ 3. & x & +y & +z & +u & +w & = 0 \\ 4. & & & z & & +w & = 0 \\ 5. & x & & +z & +u & & = 0 \end{array}$$

Given information: $x = y = 0$. Then

$$\begin{array}{l} 2. \implies z = 0, \\ 1. \implies u = 0, \\ 3. \implies w = 0. \end{array}$$

Hidden triangle in a system

$$\begin{array}{rcccccc} 2. & & y & +z & +0 & +0 & = 0 \\ 1. & x & & +z & +u & +0 & = 0 \\ 3. & x & +y & +z & +u & +w & = 0 \\ 4. & & & z & & +w & = 0 \\ 5. & x & & +z & +u & & = 0 \end{array}$$

Given information: $x = y = 0$. Then

$$2. \implies z = 0,$$

$$1. \implies u = 0,$$

$$3. \implies w = 0.$$

As long as the **red** terms has nonzero coefficients and the **orange** terms are zero, the same argument always works.

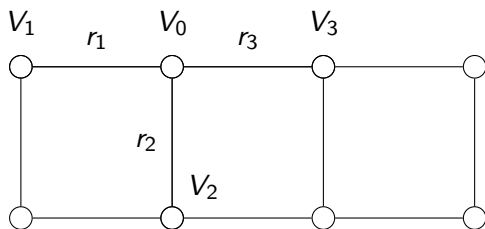
Application to algebra

Find the inverse of a formal power series.

$$\begin{array}{r} 1 \quad +2x \quad +3x^2 \quad +4x^3 \quad +5x^4 \quad +\cdots \\ \times) \quad b_0 \quad +b_1x \quad +b_2x^2 \quad +b_3x^3 \quad +b_4x^4 \quad +\cdots \\ \hline 1 \end{array}$$

Electronic circuit

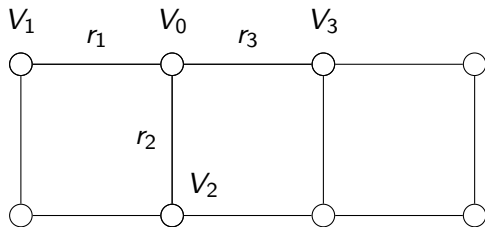
$$\frac{1}{r_1}(V_1 - V_0) + \frac{1}{r_2}(V_2 - V_0) + \frac{1}{r_3}(V_3 - V_0) + \epsilon V_0 = 0$$



Electronic circuit

$$\frac{1}{r_1}(V_1 - V_0) + \frac{1}{r_2}(V_2 - V_0) + \frac{1}{r_3}(V_3 - V_0) + \epsilon V_0 = 0$$

$$\frac{1}{r_1}V_1 + \frac{1}{r_2}V_2 + \frac{1}{r_3}V_3 + \left(\epsilon - \frac{1}{r_1} - \frac{1}{r_2} - \frac{1}{r_3}\right)V_0 = 0$$

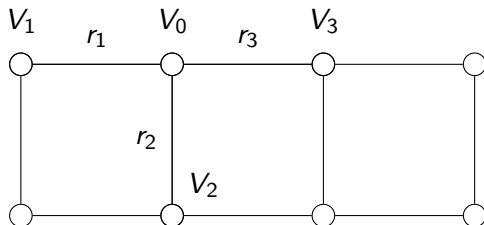


Electronic circuit

$$\frac{1}{r_1} V_1 + \frac{1}{r_2} V_2 + \frac{1}{r_3} V_3 + \left(\epsilon - \frac{1}{r_1} - \frac{1}{r_2} - \frac{1}{r_3}\right) V_0 = 0$$

$$a_1 V_1 + a_2 V_2 + a_3 V_3 + a_0 V_0 = 0$$

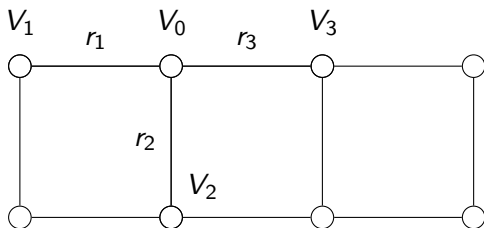
nonzero zero or nonzero



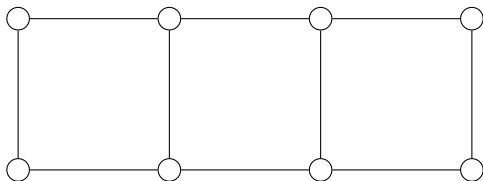
Electronic circuit

$$a_1 V_1 + \underset{\text{nonzero}}{a_2} V_2 + \underset{\text{zero or nonzero}}{a_3} V_3 + a_0 V_0 = 0$$

The conservation law leads to a linear equation on each node; itself and its neighbors represent the variables.

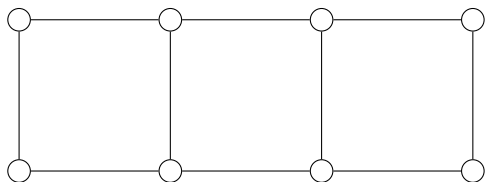



How many sensors required to monitor the voltages?



- ▶ Each vertex represents a linear equation; variables are itself and its neighbors (closed neighborhood).
- ▶ If in a closed neighborhood, all but one voltages are known, then this remaining one are also known.

How many sensors required to monitor the voltages?



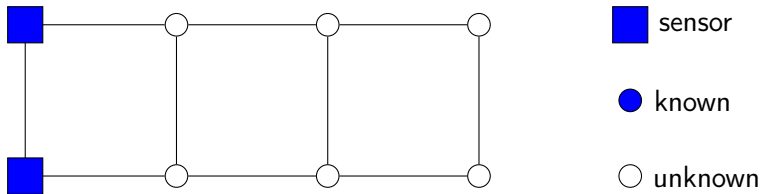
 sensor

 known

 unknown

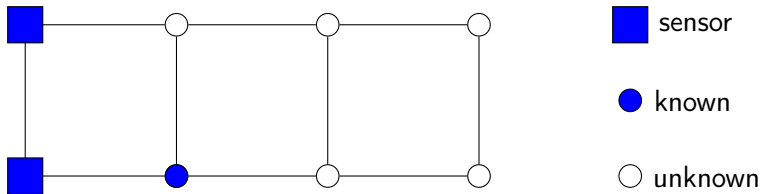
- ▶ Each vertex represents a linear equation; variables are itself and its neighbors (closed neighborhood).
- ▶ If in a closed neighborhood, all but one voltages are known, then this remaining one are also known.

How many sensors required to monitor the voltages?



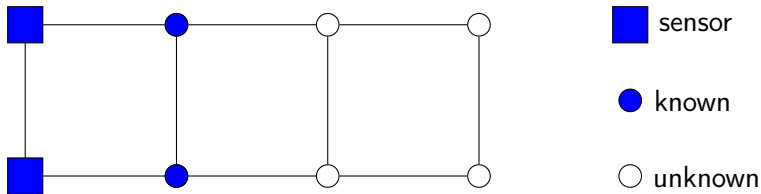
- ▶ Each vertex represents a linear equation; variables are itself and its neighbors (closed neighborhood).
- ▶ If in a closed neighborhood, all but one voltages are known, then this remaining one are also known.

How many sensors required to monitor the voltages?



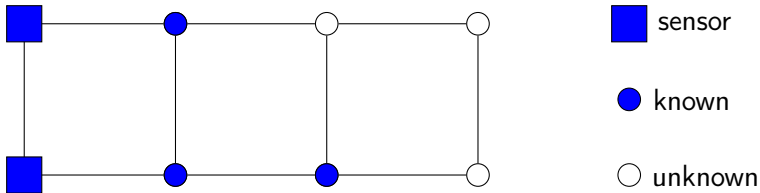
- ▶ Each vertex represents a linear equation; variables are itself and its neighbors (closed neighborhood).
- ▶ If in a closed neighborhood, all but one voltages are known, then this remaining one are also known.

How many sensors required to monitor the voltages?



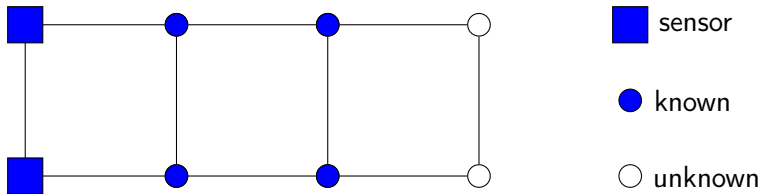
- ▶ Each vertex represents a linear equation; variables are itself and its neighbors (closed neighborhood).
- ▶ If in a closed neighborhood, all but one voltages are known, then this remaining one are also known.

How many sensors required to monitor the voltages?



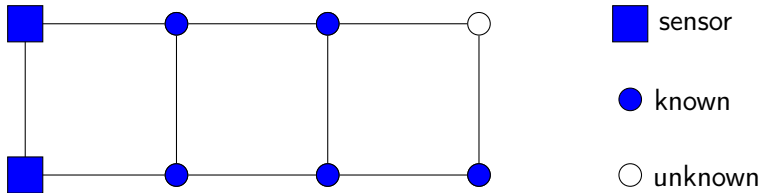
- ▶ Each vertex represents a linear equation; variables are itself and its neighbors (closed neighborhood).
- ▶ If in a closed neighborhood, all but one voltages are known, then this remaining one are also known.

How many sensors required to monitor the voltages?



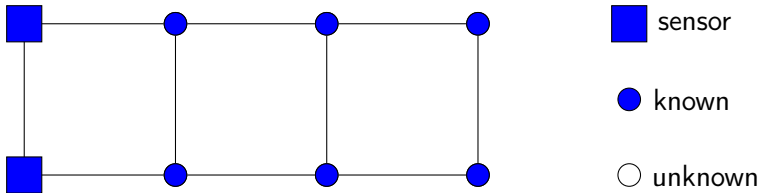
- ▶ Each vertex represents a linear equation; variables are itself and its neighbors (closed neighborhood).
- ▶ If in a closed neighborhood, all but one voltages are known, then this remaining one are also known.

How many sensors required to monitor the voltages?



- ▶ Each vertex represents a linear equation; variables are itself and its neighbors (closed neighborhood).
- ▶ If in a closed neighborhood, all but one voltages are known, then this remaining one are also known.

How many sensors required to monitor the voltages?



- ▶ Each vertex represents a linear equation; variables are itself and its neighbors (closed neighborhood).
- ▶ If in a closed neighborhood, all but one voltages are known, then this remaining one are also known.

Model by graphs and matrices

- ▶ A electronic circuit can be represented by a **graph**; each vertex represents a node, and each edge represents a connection.
- ▶ The linear equations can be recorded into a **matrix**; each row represents a equation, and each column represents an unknown voltage.
- ▶ This is a symmetric matrix where rows and columns are both indexed by the vertices.

Model by graphs and matrices

- ▶ A electronic circuit can be represented by a **graph**; each vertex represents a node, and each edge represents a connection.
- ▶ The linear equations can be recorded into a **matrix**; each row represents a equation, and each column represents an unknown voltage.
- ▶ This is a symmetric matrix where rows and columns are both indexed by the vertices.

Model by graphs and matrices

- ▶ A electronic circuit can be represented by a **graph**; each vertex represents a node, and each edge represents a connection.
- ▶ The linear equations can be recorded into a **matrix**; each row represents a equation, and each column represents an unknown voltage.
- ▶ This is a symmetric matrix where rows and columns are both indexed by the vertices.

Let G be a simple graph on n vertices. The family $\mathcal{S}(G)$ consists of all $n \times n$ real symmetric matrix $M = [M_{i,j}]$ with

$$\begin{cases} M_{i,j} = 0 & \text{if } i \neq j \text{ and } \{i,j\} \text{ is not an edge,} \\ M_{i,j} \neq 0 & \text{if } i \neq j \text{ and } \{i,j\} \text{ is an edge,} \\ M_{i,j} \in \mathbb{R} & \text{if } i = j. \end{cases}$$

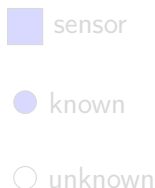
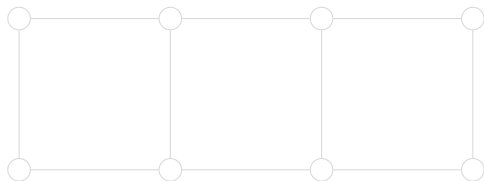
$$\mathcal{S}(\text{---}\circ\text{---}\circ\text{---}\circ) \ni \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}, \begin{bmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{bmatrix}, \begin{bmatrix} 2 & 0.1 & 0 \\ 0.1 & 1 & \pi \\ 0 & \pi & 0 \end{bmatrix}, \dots$$

Zero forcing

Zero forcing process:

- ▶ Start with a given set of blue vertices (sensors).
- ▶ If for some x , the closed neighborhood $N_G[x]$ are all blue except for one vertex y and $y \neq x$, then y turns blue.

An initial blue set that can make the whole graph blue is called a **zero forcing set**. The **zero forcing number** $Z(G)$ of a graph G is the minimum size of a zero forcing set.

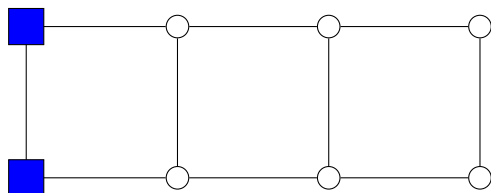


Zero forcing

Zero forcing process:

- ▶ Start with a given set of blue vertices (sensors).
- ▶ If for some x , the closed neighborhood $N_G[x]$ are all blue except for one vertex y and $y \neq x$, then y turns blue.

An initial blue set that can make the whole graph blue is called a **zero forcing set**. The **zero forcing number** $Z(G)$ of a graph G is the minimum size of a zero forcing set.



 sensor

 known

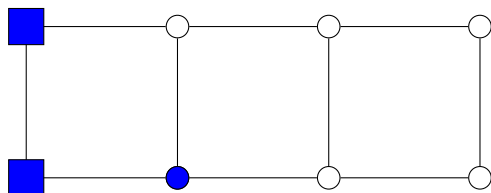
 unknown


Zero forcing

Zero forcing process:

- ▶ Start with a given set of blue vertices (sensors).
- ▶ If for some x , the closed neighborhood $N_G[x]$ are all blue except for one vertex y and $y \neq x$, then y turns blue.

An initial blue set that can make the whole graph blue is called a **zero forcing set**. The **zero forcing number** $Z(G)$ of a graph G is the minimum size of a zero forcing set.



 sensor

 known

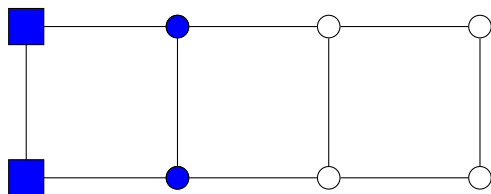
 unknown


Zero forcing

Zero forcing process:

- ▶ Start with a given set of blue vertices (sensors).
- ▶ If for some x , the closed neighborhood $N_G[x]$ are all blue except for one vertex y and $y \neq x$, then y turns blue.

An initial blue set that can make the whole graph blue is called a **zero forcing set**. The **zero forcing number** $Z(G)$ of a graph G is the minimum size of a zero forcing set.



 sensor

 known

 unknown

How to deploy the sensors?

*Any **zero forcing set** is a good deployment of sensors that can monitor the whole graph.*

*The **zero forcing number** is the minimum number of sensors required.*

Zero forcing sets suggest a good deployment **before** knowing the details of the network.

Many studies are done on zero forcing and its variation **power domination**.

How to deploy the sensors?

Any *zero forcing set* is a good deployment of sensors that can monitor the whole graph.

The *zero forcing number* is the minimum number of sensors required.

Zero forcing sets suggest a good deployment **before** knowing the details of the network.

Many studies are done on zero forcing and its variation **power domination**.

How to deploy the sensors?

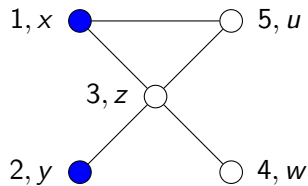
*Any **zero forcing set** is a good deployment of sensors that can monitor the whole graph.*

*The **zero forcing number** is the minimum number of sensors required.*

Zero forcing sets suggest a good deployment **before** knowing the details of the network.

Many studies are done on zero forcing and its variation **power domination**.

Hidden triangle revisit



Given blue vertices: 1 and 2.

Then

$$2 \rightarrow 3,$$

$$1 \rightarrow 5,$$

$$3 \rightarrow 4.$$

$$\begin{array}{rcccccc} 1. & x & & +z & & +u & = 0 \\ 2. & & y & +z & & & = 0 \\ 3. & x & +y & +z & +w & +u & = 0 \\ 4. & & & z & +w & & = 0 \\ 5. & x & & +z & & +u & = 0 \end{array}$$

Given information: $x = y = 0$.

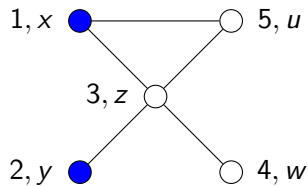
Then

$$2. \implies z = 0,$$

$$1. \implies u = 0,$$

$$3. \implies w = 0.$$

Hidden triangle revisit



Given blue vertices: 1 and 2.

Then

$$2 \rightarrow 3,$$

$$1 \rightarrow 5,$$

$$3 \rightarrow 4.$$

$$\begin{array}{rclclcl} 2. & & y & +z & +0 & +0 & = 0 \\ 1. & x & & +z & +u & +0 & = 0 \\ 3. & x & +y & +z & +u & +w & = 0 \\ 4. & & & z & & +w & = 0 \\ 5. & x & & +z & +u & & = 0 \end{array}$$

Given information: $x = y = 0$.

Then

$$2. \implies z = 0,$$

$$1. \implies u = 0,$$

$$3. \implies w = 0.$$

Proposition (Kenter and L 2018)

Let G be a graph on the vertex set V . The following are equivalent:

1. B is a zero forcing set.
2. For any $A \in \mathcal{S}(G)$, the columns corresponding to $V \setminus B$ hides a lower triangular matrix.
3. For any $A \in \mathcal{S}(G)$, the columns corresponding to $V \setminus B$ are linearly independent.

Theorem (AIM Work Group 2008)

Let G be a graph on n vertices. Then for any matrix $A \in \mathcal{S}(G)$,
 $n - Z(G) \leq \text{rank}(A)$.

More zero forcing

- ▶ Same argument works for non-symmetric matrices.
- ▶ When more information are known on the matrices, the design of the zero forcing process can be improved.
- ▶ For example, nonnegative matrices, zero diagonal entries, or nonzero diagonal entries.
- ▶ They all follow the same philosophy.
- ▶ Zero forcing is related to the minimum rank problem (Math), quantum control (Physics), building logic circuit (Physics), the graph searching problem (ComS).

More zero forcing

- ▶ Same argument works for non-symmetric matrices.
- ▶ When more information are known on the matrices, the design of the zero forcing process can be improved.
- ▶ For example, nonnegative matrices, zero diagonal entries, or nonzero diagonal entries.
- ▶ They all follow the same philosophy.
- ▶ Zero forcing is related to the minimum rank problem (Math), quantum control (Physics), building logic circuit (Physics), the graph searching problem (ComS).

More zero forcing

- ▶ Same argument works for non-symmetric matrices.
- ▶ When more information are known on the matrices, the design of the zero forcing process can be improved.
- ▶ For example, nonnegative matrices, zero diagonal entries, or nonzero diagonal entries.
- ▶ They all follow the same philosophy.
- ▶ Zero forcing is related to the minimum rank problem (Math), quantum control (Physics), building logic circuit (Physics), the graph searching problem (ComS).

More zero forcing

- ▶ Same argument works for non-symmetric matrices.
- ▶ When more information are known on the matrices, the design of the zero forcing process can be improved.
- ▶ For example, nonnegative matrices, zero diagonal entries, or nonzero diagonal entries.
- ▶ They all follow the same philosophy.
- ▶ Zero forcing is related to the minimum rank problem (Math), quantum control (Physics), building logic circuit (Physics), the graph searching problem (ComS).

More zero forcing

- ▶ Same argument works for non-symmetric matrices.
- ▶ When more information are known on the matrices, the design of the zero forcing process can be improved.
- ▶ For example, nonnegative matrices, zero diagonal entries, or nonzero diagonal entries.
- ▶ They all follow the same philosophy.
- ▶ Zero forcing is related to the minimum rank problem (Math), quantum control (Physics), building logic circuit (Physics), the graph searching problem (ComS).

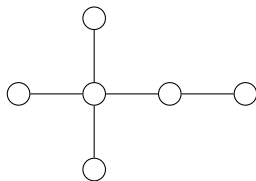
Domination number and zero forcing

Zero forcing with nonzero diagonal

Color change rule:

*If for some x , the **closed neighbourhood** $N_G[x]$ are all blue except for one vertex y , then y turns blue.*

$Z_\ell(G)$ = minimum size of a zero forcing set.

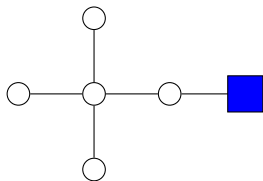


Zero forcing with nonzero diagonal

Color change rule:

*If for some x , the **closed neighbourhood** $N_G[x]$ are all blue except for one vertex y , then y turns blue.*

$Z_\ell(G)$ = minimum size of a zero forcing set.

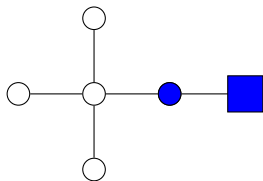


Zero forcing with nonzero diagonal

Color change rule:

*If for some x , the **closed neighbourhood** $N_G[x]$ are all blue except for one vertex y , then y turns blue.*

$Z_\ell(G)$ = minimum size of a zero forcing set.

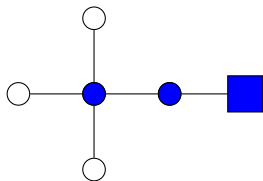


Zero forcing with nonzero diagonal

Color change rule:

*If for some x , the **closed neighbourhood** $N_G[x]$ are all blue except for one vertex y , then y turns blue.*

$Z_\ell(G)$ = minimum size of a zero forcing set.

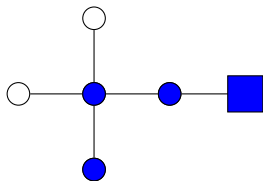


Zero forcing with nonzero diagonal

Color change rule:

*If for some x , the **closed neighbourhood** $N_G[x]$ are all blue except for one vertex y , then y turns blue.*

$Z_\ell(G)$ = minimum size of a zero forcing set.

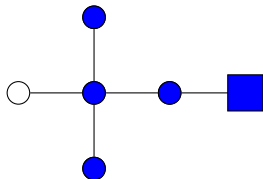


Zero forcing with nonzero diagonal

Color change rule:

*If for some x , the **closed neighbourhood** $N_G[x]$ are all blue except for one vertex y , then y turns blue.*

$Z_\ell(G)$ = minimum size of a zero forcing set.

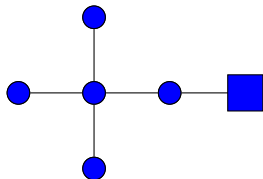


Zero forcing with nonzero diagonal

Color change rule:

*If for some x , the **closed neighbourhood** $N_G[x]$ are all blue except for one vertex y , then y turns blue.*

$Z_\ell(G)$ = minimum size of a zero forcing set.

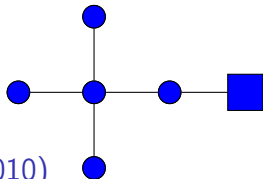


Zero forcing with nonzero diagonal

Color change rule:

If for some x , the *closed neighbourhood* $N_G[x]$ are all blue except for one vertex y , then y turns blue.

$Z_i(G)$ = minimum size of a zero forcing set.



Theorem (Hogben 2010)

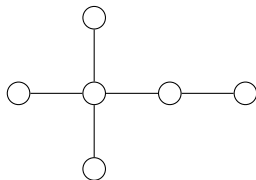
Let G be a graph on n vertices. Then $n - Z_i(G) \leq \text{rank}(A)$ for any $A \in \mathcal{S}(G)$ with *nonzero diagonal entries*.

Zero forcing with zero diagonal

Color change rule:

*If for some x , the **open neighbourhood** $N_G(x)$ are all blue except for one vertex y , then y turns blue.*

$Z_-(G)$ = minimum size of a zero forcing set.

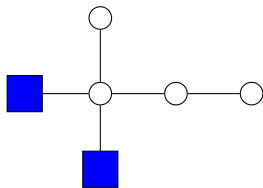


Zero forcing with zero diagonal

Color change rule:

*If for some x , the **open neighbourhood** $N_G(x)$ are all blue except for one vertex y , then y turns blue.*

$Z_-(G)$ = minimum size of a zero forcing set.

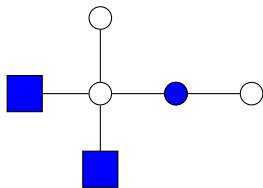


Zero forcing with zero diagonal

Color change rule:

*If for some x , the **open neighbourhood** $N_G(x)$ are all blue except for one vertex y , then y turns blue.*

$Z_-(G)$ = minimum size of a zero forcing set.

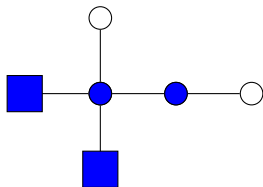


Zero forcing with zero diagonal

Color change rule:

*If for some x , the **open neighbourhood** $N_G(x)$ are all blue except for one vertex y , then y turns blue.*

$Z_-(G)$ = minimum size of a zero forcing set.

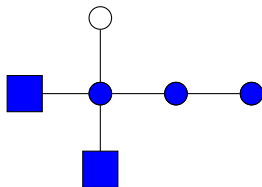


Zero forcing with zero diagonal

Color change rule:

*If for some x , the **open neighbourhood** $N_G(x)$ are all blue except for one vertex y , then y turns blue.*

$Z_-(G)$ = minimum size of a zero forcing set.

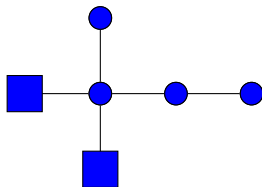


Zero forcing with zero diagonal

Color change rule:

*If for some x , the **open neighbourhood** $N_G(x)$ are all blue except for one vertex y , then y turns blue.*

$Z_-(G)$ = minimum size of a zero forcing set.

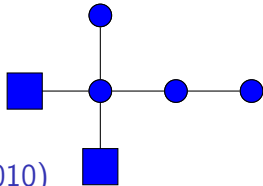


Zero forcing with zero diagonal

Color change rule:

If for some x , the open neighbourhood $N_G(x)$ are all blue except for one vertex y , then y turns blue.

$Z_-(G)$ = minimum size of a zero forcing set.



Theorem (Hogben 2010)

Let G be a graph on n vertices. Then $n - Z_-(G) \leq \text{rank}(A)$ for any $A \in \mathcal{S}(G)$ with zero diagonal entries.

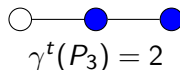
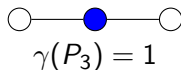
Domination number

Let G be a graph. The **domination number** $\gamma(G)$ is the minimum cardinality of a set X such that

$$\bigcup_{x \in X} N_G[x] = V(G).$$

The **total domination number** $\gamma^t(G)$ is the minimum cardinality of a set X such that

$$\bigcup_{x \in X} N_G(x) = V(G).$$



Greedy algorithm

- ▶ Greedy algorithm follows the problem solving heuristic of **making the locally optimal choice** at each stage with the hope of finding a global optimum.
- ▶ Greedy algorithm for domination number: When X are chosen and not yet dominate the whole graph, pick a vertex v such that

$$N_G[v] \setminus \bigcup_{x \in X} N_G[x] \neq \emptyset.$$

Greedy algorithm

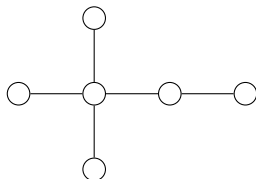
- ▶ Greedy algorithm follows the problem solving heuristic of **making the locally optimal choice** at each stage with the hope of finding a global optimum.
- ▶ Greedy algorithm for domination number: When X are chosen and not yet dominate the whole graph, pick a vertex v such that

$$N_G[v] \setminus \bigcup_{x \in X} N_G[x] \neq \emptyset.$$

Grundy domination number

The **Grundy domination number** $\gamma_{\text{gr}}(G)$ is the length of the longest sequence (v_1, v_2, \dots, v_k) such that

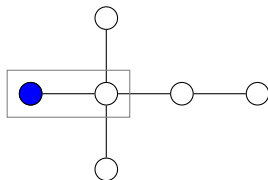
$$N_G[v_i] \setminus \bigcup_{j=1}^{i-1} N_G[v_j] \neq \emptyset.$$



Grundy domination number

The **Grundy domination number** $\gamma_{\text{gr}}(G)$ is the length of the longest sequence (v_1, v_2, \dots, v_k) such that

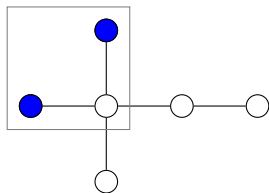
$$N_G[v_i] \setminus \bigcup_{j=1}^{i-1} N_G[v_j] \neq \emptyset.$$



Grundy domination number

The **Grundy domination number** $\gamma_{\text{gr}}(G)$ is the length of the longest sequence (v_1, v_2, \dots, v_k) such that

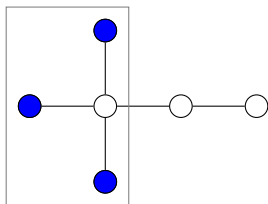
$$N_G[v_i] \setminus \bigcup_{j=1}^{i-1} N_G[v_j] \neq \emptyset.$$



Grundy domination number

The **Grundy domination number** $\gamma_{\text{gr}}(G)$ is the length of the longest sequence (v_1, v_2, \dots, v_k) such that

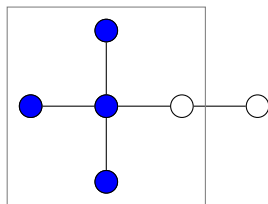
$$N_G[v_i] \setminus \bigcup_{j=1}^{i-1} N_G[v_j] \neq \emptyset.$$



Grundy domination number

The **Grundy domination number** $\gamma_{\text{gr}}(G)$ is the length of the longest sequence (v_1, v_2, \dots, v_k) such that

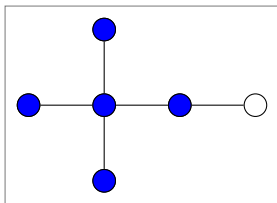
$$N_G[v_i] \setminus \bigcup_{j=1}^{i-1} N_G[v_j] \neq \emptyset.$$



Grundy domination number

The **Grundy domination number** $\gamma_{\text{gr}}(G)$ is the length of the longest sequence (v_1, v_2, \dots, v_k) such that

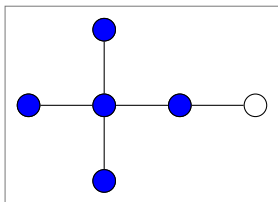
$$N_G[v_i] \setminus \bigcup_{j=1}^{i-1} N_G[v_j] \neq \emptyset.$$



Grundy domination number

The **Grundy domination number** $\gamma_{\text{gr}}(G)$ is the length of the longest sequence (v_1, v_2, \dots, v_k) such that

$$N_G[v_i] \setminus \bigcup_{j=1}^{i-1} N_G[v_j] \neq \emptyset.$$

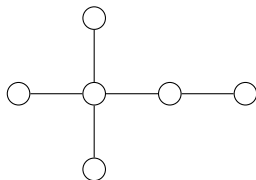


So $\gamma_{\text{gr}}(G) = 5$.

Grundy total domination number

The **Grundy total domination number** $\gamma_{\text{gr}}^t(G)$ is the length of the longest sequence (v_1, v_2, \dots, v_k) such that

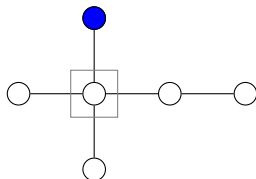
$$N_G(v_i) \setminus \bigcup_{j=1}^{i-1} N_G(v_j) \neq \emptyset.$$



Grundy total domination number

The **Grundy total domination number** $\gamma_{\text{gr}}^t(G)$ is the length of the longest sequence (v_1, v_2, \dots, v_k) such that

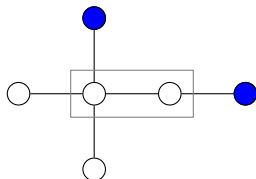
$$N_G(v_i) \setminus \bigcup_{j=1}^{i-1} N_G(v_j) \neq \emptyset.$$



Grundy total domination number

The **Grundy total domination number** $\gamma_{\text{gr}}^t(G)$ is the length of the longest sequence (v_1, v_2, \dots, v_k) such that

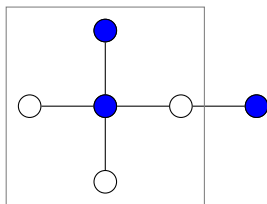
$$N_G(v_i) \setminus \bigcup_{j=1}^{i-1} N_G(v_j) \neq \emptyset.$$



Grundy total domination number

The **Grundy total domination number** $\gamma_{\text{gr}}^t(G)$ is the length of the longest sequence (v_1, v_2, \dots, v_k) such that

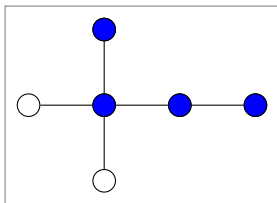
$$N_G(v_i) \setminus \bigcup_{j=1}^{i-1} N_G(v_j) \neq \emptyset.$$



Grundy total domination number

The **Grundy total domination number** $\gamma_{\text{gr}}^t(G)$ is the length of the longest sequence (v_1, v_2, \dots, v_k) such that

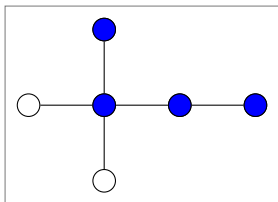
$$N_G(v_i) \setminus \bigcup_{j=1}^{i-1} N_G(v_j) \neq \emptyset.$$



Grundy total domination number

The **Grundy total domination number** $\gamma_{\text{gr}}^t(G)$ is the length of the longest sequence (v_1, v_2, \dots, v_k) such that

$$N_G(v_i) \setminus \bigcup_{j=1}^{i-1} N_G(v_j) \neq \emptyset.$$



So $\gamma_{\text{gr}}^t(G) = 4$.

Grundy domination number, zero forcing number, and the rank bound

Theorem (L 2017)

Let G be a graph on n vertices. Then

$$\gamma_{\text{gr}}(G) = n - Z_{\ell}(G) \text{ and } \gamma_{\text{gr}}^t(G) = n - Z_{-}(G).$$

Therefore,

$$\gamma_{\text{gr}}(G) \leq \text{rank}(A)$$

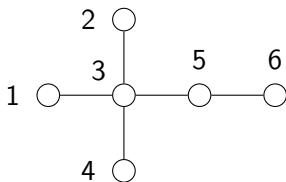
for any $A \in S(G)$ with diagonal entries all nonzero; and

$$\gamma_{\text{gr}}^t(G) \leq \text{rank}(A)$$

for any $A \in S(G)$ with zero diagonal.

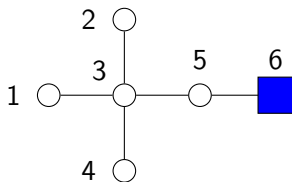
Proof of the theorem

Key: Reverse the forcing process!



Proof of the theorem

Key: Reverse the forcing process!



$$6 \rightarrow 5$$

$$5 \rightarrow 3$$

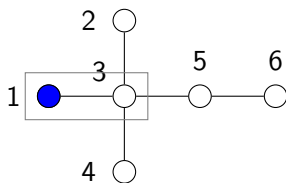
$$4 \rightarrow 4$$

$$2 \rightarrow 2$$

$$3 \rightarrow 1$$

Proof of the theorem

Key: Reverse the forcing process!



$$6 \rightarrow 5$$

$$5 \rightarrow 3$$

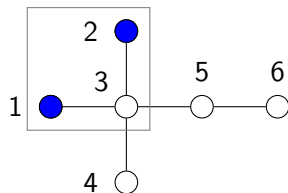
$$4 \rightarrow 4$$

$$2 \rightarrow 2$$

$$3 \rightarrow 1$$

Proof of the theorem

Key: Reverse the forcing process!



$$6 \rightarrow 5$$

$$5 \rightarrow 3$$

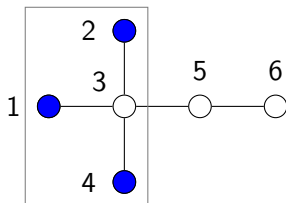
$$4 \rightarrow 4$$

$$2 \rightarrow 2$$

$$3 \rightarrow 1$$

Proof of the theorem

Key: Reverse the forcing process!



$$6 \rightarrow 5$$

$$5 \rightarrow 3$$

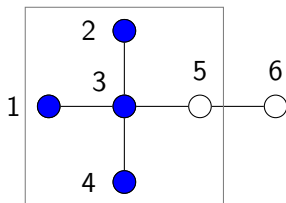
$$4 \rightarrow 4$$

$$2 \rightarrow 2$$

$$3 \rightarrow 1$$

Proof of the theorem

Key: Reverse the forcing process!



$6 \rightarrow 5$

$5 \rightarrow 3$

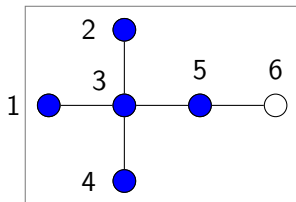
$4 \rightarrow 4$

$2 \rightarrow 2$

$3 \rightarrow 1$

Proof of the theorem

Key: Reverse the forcing process!



$$6 \rightarrow 5$$

$$5 \rightarrow 3$$

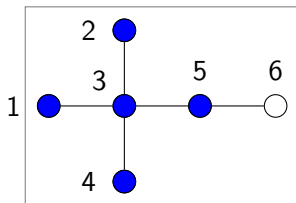
$$4 \rightarrow 4$$

$$2 \rightarrow 2$$

$$3 \rightarrow 1$$

Proof of the theorem

Key: Reverse the forcing process!



$6 \rightarrow 5$

$5 \rightarrow 3$



$4 \rightarrow 4$

$2 \rightarrow 2$




$3 \rightarrow 1$

Thank you!

References I

-  AIM Minimum Rank – Special Graphs Work Group (F. Barioli, W. Barrett, S. Butler, S. M. Cioabă, D. Cvetković, S. M. Fallat, C. Godsil, W. H. Haemers, L. Hogben, R. Mikkelsen, S. K. Narayan, O. Pryporova, I. Sciriha, W. So, D. Stevanović, H. van der Holst, K. Vander Meulen, and A. Wangsness).
Zero forcing sets and the minimum rank of graphs.
Linear Algebra Appl., 428:1628–1648, 2008.
-  D. Burgarth and V. Giovannetti.
Full control by locally induced relaxation.
Phys. Rev. Lett., 99:100501, 2007.

References II

-  D. Burgarth, V. Giovannetti, L. Hogben, S. Severini, and M. Young.
Logic circuits from zero forcing.
Nat. Comput., 14:485–490, 2015.
-  S. M. Fallat, K. Meagher, and B. Yang.
On the complexity of the positive semidefinite zero forcing number.
Linear Algebra Appl., 491:101–122, 2016.
-  L. Hogben.
Minimum rank problems.
Linear Algebra Appl., 432:1961–1974, 2010.

References III



F. H. J. Kenter and J. C.-H. Lin.

On the error of a priori sampling: Zero forcing sets and propagation time.

Linear Algebra Appl., 576:124–141, 2019.



J. C.-H. Lin.

Zero forcing number, Grundy domination number, and their variants.

Linear Algebra Appl., 563:240–254, 2019.