

An efficient Wave Based Method for solving Helmholtz problems in three-dimensional bounded domains

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Numerical validation of the WBM for 3D acoustics



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- Vibro-acoustics Numerical modelling
- WBM
- Numerical validation
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Introduction

- Vibro-acoustic interactions
- Numerical modelling approaches for mid-frequency vibro-acoustic problems

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Vibro-acoustic interactions



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Vibro-acoustic interactions



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Available approaches

Deterministic element based methods: FEM, BEM,...

- approximating shape functions
- fine discretisations

 $\Rightarrow \text{low-frequency}$





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Available approaches

Statistical energy based methods: SEA, EFEM,...

- energy in SEA subsystems
- underlying assumptions

 \Rightarrow high-frequency





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Wave Based Method

Deterministic element based methods: FEM, BEM,...

- approximating shape functions
- fine discretisations

 \Rightarrow low-frequency

Statistical energy based methods: SEA, EFEM,...

- energy in SEA subsystems
- underlying assumptions

 \Rightarrow high-frequency

Deterministic Trefftz-based Wave Based Method

- Basis functions = exact solutions of governing equations
- Enhanced numerical convergence properties

 \Rightarrow applicable to mid-frequency problems





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 - Problem definition
 - Wave Based modelling approach

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Dynamic equations: Helmholtz problems



• Steady-state dynamic acoustic pressure *p*(**r**) in *V*: Helmholtz equation

$$abla^2 p(\mathbf{r}) + k^2 p(\mathbf{r}) = \mathcal{F}(\mathbf{r}), \mathbf{r} \in \Omega$$

At each point of Ω_•: 1 boundary condition

$$\begin{bmatrix} \mathbf{r} \in \Omega_{\nu} : \mathcal{L}_{\nu}(p(\mathbf{r})) = \bar{\nu}_{n}(\mathbf{r}) ,\\ \mathbf{r} \in \Omega_{Z} : \mathcal{L}_{\nu}(p(\mathbf{r})) = p(\mathbf{r})/\bar{Z}_{n}(\mathbf{r}) ,\\ \mathbf{r} \in \Omega_{p} : p(\mathbf{r}) = \bar{p}(\mathbf{r}) . \end{bmatrix}$$



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WBM modelling approach

General WBM modelling process

Approximation of the field variables within each of the subdomains using physically meaningful wave functions en source terms

WBM approximation

$$p^{(\alpha)}(\mathbf{r}) \simeq \sum p_w^{(\alpha)} \Phi_w^{(\alpha)}(\mathbf{r}) + \hat{p}_q^{(\alpha)}(\mathbf{r})$$



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WBM modelling approach

General WBM modelling process

- Approximation of the field variables within each of the subdomains using physically meaningful wave functions en source terms
- Minimisation of the approximation errors using a Galerkin weighted residual formulation

$$egin{aligned} &\int_{\Omega_
u} \widetilde{p}(\mathbf{r}) \; R_
u(\mathbf{r}) d\Omega + \int_{\Omega_Z} \widetilde{p}(\mathbf{r}) \; R_Z(\mathbf{r}) \mathrm{d}\Omega \ &+ \int_{\Omega_p} -\mathcal{L}_
u(\widetilde{p}(\mathbf{r})) \; R_p(\mathbf{r}) d\Omega = 0 \end{aligned}$$



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General WBM modelling process

- Approximation of the field variables within each of the subdomains using physically meaningful wave functions en source terms
- Minimisation of the approximation errors using a Galerkin weighted residual formulation
- Solution of the resulting system of equations

$$\begin{bmatrix} A_w^1 & \cdots & C_w^{1,N_\Omega} \\ \vdots & \ddots & \vdots \\ C_w^{N_\Omega,1} & \cdots & A_w^{N_\Omega} \end{bmatrix} \begin{cases} p_w^1 \\ \vdots \\ p_w^{N_\Omega} \end{cases} = \begin{cases} F_w^1 \\ \vdots \\ F_w^{N_\Omega} \end{cases}$$



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WBM modelling approach

General WBM modelling process

- Approximation of the field variables within each of the subdomains using physically meaningful wave functions en source terms
- Minimisation of the approximation errors using a Galerkin weighted residual formulation
- Solution of the resulting system of equations
- Postprocessing, visualisation and interpretation of the response fields





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WBM modelling approach

Applications areas

The WB modelling approach has been successfully applied to

2D steady-state acoustic analysis

- multi-domain interior acoustics
- acoustic scattering problems
- multiple scattering and inclusion problems

2D steady-state structural dynamic analysis

- plate membrane problems
- plate bending problems
- shell analysis

2D steady-state vibro-acoustic analysis

- interior vibro-acoustics
- exterior vibro-acoustics

Current extension:

• 3D steady-state interior acoustics



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WBM field variable approximations

Acoustic pressure expansion: bounded subdomains

$$p^{(\alpha)}(\mathbf{r}) \simeq \sum_{w=1}^{n_w^{(\alpha)}} p_w^{(\alpha)} \Phi_w^{(\alpha)}(\mathbf{r}) + \hat{p}_q^{(\alpha)}(\mathbf{r})$$

 $\Phi_{w}^{(\alpha)}(\mathbf{r}(x,y))$: *Homogeneous* solutions of Helmholtz eq.

$$\Phi_{w}(\mathbf{r}(x, y, z)) = \begin{cases} \Phi_{w_{r}}(x, y, z) = \cos(k_{xw_{r}}x) \cos(k_{yw_{r}}y) e^{-jk_{zw_{r}}z} \\ \Phi_{w_{s}}(x, y, z) = \cos(k_{xw_{s}}x) e^{-jk_{yw_{s}}y} \cos(k_{zw_{s}}z) \\ \Phi_{w_{t}}(x, y, z) = e^{-jk_{xw_{t}}x} \cos(k_{yw_{t}}y) \cos(k_{zw_{t}}z) \end{cases}$$

Trefftz approach: the wave number components should satisfy the associated dispersion relation:

$$(k_{xw_r})^2 + (k_{yw_r})^2 + (k_{zw_r})^2 = (k_{xw_s})^2 + (k_{yw_s})^2 + (k_{zw_s})^2 = (k_{xw_t})^2 + (k_{yw_t})^2 + (k_{zw_t})^2 = k^2$$



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Acoustic pressure expansion: bounded subdomains

$$p^{(\alpha)}(\mathbf{r}) \simeq \sum_{w=1}^{n_w^{(\alpha)}} p_w^{(\alpha)} \Phi_w^{(\alpha)}(\mathbf{r}) + \hat{p}_q^{(\alpha)}(\mathbf{r})$$

 ∞ number of solutions \rightarrow selection of wave numbers:



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WBM approximations: wave functions

$$p^{(\alpha)}(\mathbf{r}) \simeq \sum_{w} p_{w}^{(\alpha)} \Phi_{w}^{(\alpha)}(\mathbf{r}) + \hat{p}_{q}^{(\alpha)}(\mathbf{r})$$





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\$\heta_q^{(\alpha)}(x,y,z)\$: Particular (free field) solution of Helmholtz eq.
 Acoustic point source:

$$\widehat{p}_q(x, y, z) = rac{j
ho_0 \omega Q}{4 \pi} rac{e^{-jkr_q}}{r_q}$$

with *Q* the source strength $Q = \int_V q \, dV$ and with r_q the distance to the source point.



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WBM approximation: source terms

$$p^{(\alpha)}(\mathbf{r}) \simeq \sum_{w} p_{w}^{(\alpha)} \Phi_{w}^{(\alpha)}(\mathbf{r}) + \hat{p}_{q}^{(\alpha)}(\mathbf{r})$$





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Application of a Galerkin weighted residual formulation yields

$$\left[\begin{array}{ccc} A_w^1 & \cdots & C_w^{1,N_\Omega} \\ \vdots & \ddots & \vdots \\ C_w^{N_\Omega,1} & \cdots & A_w^{N_\Omega} \end{array}\right] \left\{\begin{array}{c} p_w^1 \\ \vdots \\ p_w^{N_\Omega} \end{array}\right\} = \left\{\begin{array}{c} F_w^1 \\ \vdots \\ F_w^{N_\Omega} \end{array}\right\}$$

Properties:

- + Small number of degrees of freedom
- + No accuracy decrease for derived variables
- + High convergence rate
- Fully populated matrices with complex coefficients
- Frequency-dependent matrices
- More complex numerical integrations
- Bad numerical conditioning
- Convergence only guaranteed for convex (sub)domains
 - \rightarrow applicable to practical mid-frequency applications of moderate geometrical complexity



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- Problem setting
- Spatial results
- Efficiency
- Conclusions

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The Wave Based Method

Numerical validation of the WBM for 3D acoustics

Overview

- Problem setting
- Spatial predictions of acoustic quantities
- Computational efficiency comparison

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Numerical validation

Convex acoustic cavity



Acoustic fluid: Air

 $c = 340\sqrt{1+j\eta} \ {\rm m/s}, \ \rho_0 = 1.225/(1+j\eta) \ {\rm kg/m^3}, \ \eta = \{0\%.1\%\}$

- Boundary conditions: acoustically rigid ($\bar{v}_n(\mathbf{r}) = 0$)
- Excitation: discontinuous unit normal velocity on patch in front



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Numerical validation

Convex acoustic cavity

Acoustic variables at 450Hz, damped case

• Acoustic pressure amplitude [Pa]





WBM

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Numerical validation

Convex acoustic cavity

Acoustic variables at 450Hz, damped case

• Acoustic velocity vector field [m/s]



Discontinuous velocity excitation conditions accurately taken into account



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Numerical validation

Convex acoustic cavity

Computational efficiency comparison at 450Hz





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Numerical validation

Convex acoustic cavity

Frequency response comparison damped problem setting





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Relative pressure amplitude prediction errors damped problem setting



- For a similar calculation time, the WBM is an order of magnitude more accurate than the quadratic FEM
- WBM reaches a similar prediction accuracy more than 10 times faster than the quadratic FEM.



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Wave Based Method for steady-state dynamics

Conclusions

- + globally defined exact solutions = wave functions
- + low, mid (and high) frequency applications

Extension to 3D acoustics

- Derivation of wave function sets
- Weighted residual formulation
- ⇒ Efficient modelling of 3D problems of moderate geometrical complexity



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Wave Based Method for steady-state dynamics

- + globally defined exact solutions = wave functions
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Extension to 3D acoustics

- Derivation of wave function sets
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Next steps

Extension of the modelling approach to:

- 3D multi-domain acoustic problems
- 3D acoustic (multiple) scattering problems
- 3D acoustic multiple inclusion problems



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Thank you for your attention!

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