# ISOMETRIC SHIFTS ON $C_{0}(X)$ 

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#### Abstract

For a linear isometry $T: C_{0}(X) \longrightarrow C_{0}(Y)$ of finite corank, there is a cofinite subset $Y_{1}$ of $Y$ such that $T f_{\mid Y_{1}}=h \cdot f \circ \varphi$ is a weighted composition operator and $X$ is homeomorphic to a quotient space of $Y_{1}$ modulo a finite subset. When $X=Y$, such a $T$ is called an isometric quasi- $n$-shift on $C_{0}(X)$. In this case, the action of $T$ can be implemented as a shift on a tree-like structure, called a $T$-tree, in $M(X)$ with exactly $n$ joints. The $T$-tree is total in $M(X)$ when $T$ is a shift. With this tools, we can analyze the structure of $T$.


## 1. Introduction

Let $T$ be a linear isometry from an infinite dimensional separable Hilbert space $H$ into $H$ of finite corank $n$. The von Neumann-Wold Decomposition Theorem (see e.g. [4, p. 112]) states that $T$ can be written as a direct sum of a unitary and a product of $n$ copies of the unilateral shift. More precisely, $H_{u}=\bigcap_{m=1}^{\infty} T^{m} H$ is a reducing subspace of $T$. Its orthogonal complement $H_{s}=H \ominus H_{u}$ is the infinite orthogonal sum $\bigoplus_{m=0}^{\infty} T^{m} N$, where $N=H \ominus T H$ is of dimension $n$. Now, $T_{H_{u}}$ is a unitary and $T_{\mid H_{s}}$ shifts each $n$-dimensional subspace $T^{m} N$ onto $T^{m+1} N$ for $m=0,1,2, \ldots$. In this sense, we may call $T$ an isometric quasi- $n$-shift on $H$.

We are interested in generalizing the notion of shifts and quasi-shifts to Banach spaces in a basis free setting. Generalizing a notion of Crownoven [5], we call a (necessarily bounded) linear operator $S$ from a Banach space $E$ into $E$ an $n$-shift if
(a) $S$ is injective and has closed range;
(b) $S$ has corank $n$;
(c) The intersection $\bigcap_{m=1}^{\infty} S^{m} E$ of the range spaces of all powers $S^{m}$ of $S$ is zero.
$S$ is called a quasi-n-shift if $S$ satisfies conditions (a) and (b). When $n=1$, we will simply call $S$ a shift or a quasi-shift accordingly.

In this paper, we study isometric (quasi-) $n$-shifts on continuous function spaces. Let $X$ be a locally compact Hausdorff spaces. Let $C_{0}(X)$ be the Banach space of continuous (realor complex-valued) functions defined on $X$ vanishing at infinity. In [10], Holub proved that the real Banach space $C(X, \mathbb{R})$ of continuous real-valued functions defined on $X$ admits no shift at all if $X$ is compact and connected. When the underlying field is the complex,

[^0]however, many concrete examples of such shifts was provided in [9]. The general theory of isometric shifts and quasi-shifts on continuous function spaces was built up in [8], in which Gutek et. al. posed also a number of open problems. Farid and Varadarajan [6], Rajagopalan, Rassias and Sundaresan [14, 15, 16] and Haydon [9] answered some of them. More recently, Araujo and Font [1, 7, 2] discussed related questions in this direction. The current paper extends the theory to $n$-shifts for $n \geq 1$ (and in a locally compact space setting). In particular, we provide new tools in analyzing the range spaces of such shifts.

In Section 2, we study linear isometries $T$ from $C_{0}(X)$ into $C_{0}(Y)$ of finite corank. We shall give a full description of such operators and, especially, the structure of their range spaces. In particular, we show that there is a cofinite subset $Y_{1}$ of $Y$ such that $T f_{\mid Y_{1}}=h \cdot f \circ \varphi$ is a weighted composition operator and $X$ is homeomorphic to a quotient space of $Y_{1}$ modulo a finite subset. These results are applied in Section 3 to isometric $n$-shifts and quasi- $n$-shifts on $C_{0}(X)$. In particular, we show that every isometric quasi-$n$-shift on $C_{0}(X)$ is implemented by a shift on a countable set with a tree-like structure, called a $T$-tree, with exactly $n$ joints in the dual space $M(X)$ of $C_{0}(X)$. The action of the quasi- $n$-shift is implemented as a shift on the $T$-tree. The $T$-tree is total in $M(X)$ when $T$ is a shift. An open problem stated in [8, p. 119] asks if $X$ is separable when $C_{0}(X)$ admits an isometric shift. We shall show that if $X$ does not contain infinitely many isolated points or the $T$-tree satisfies some conditions then the existence of an isometric $n$-shift $T$ on $C_{0}(X)$ ensuring the separability of $X$.

## 2. Isometries with finite corank

For a locally compact Hausdorff space $X$, we let $X_{\infty}=X \cup\{\infty\}$ be the one-point compactification of $X$ and let $C_{0}(X)=\left\{f \in C\left(X_{\infty}\right): f(\infty)=0\right\}$ be the Banach space of continuous functions on $X$ vanishing at infinity and equipped with the supremum norm. Note that the point $\infty$ at infinity is isolated in $X_{\infty}$ if and only if $X$ is compact. Let $M(X)$ be the Banach dual space of $C_{0}(X)$, which consists of all bounded regular Borel measures on $X$. Denote by $M_{1}(X)$ the closed unit ball of $M(X)$ and the set of its extreme points by

$$
\operatorname{ext} M_{1}(X)=\left\{\lambda \delta_{x} \in M_{1}(X):|\lambda|=1 \text { and } x \in X\right\}
$$

which consists of all unimodular scalar multiples of point masses $\delta_{x}$ at $x$ in $X$.
In this section, $X$ and $Y$ are locally compact Hausdorff and $T: C_{0}(X) \longrightarrow C_{0}(Y)$ is a linear isometry with the dual map $T^{*}: M(Y) \longrightarrow M(X)$. Clearly, $T^{*} \delta_{y} \in M_{1}(X)$ for all $y$ in $Y$.

Definition 2.1. We define the vanishing set of $T$ to be

$$
Y_{0}=\left\{y \in Y: T^{*} \delta_{y}=0\right\},
$$

the Holsztyński set to be

$$
Y_{1}=\left\{y \in Y: T^{*} \delta_{y} \in \operatorname{ext} M_{1}(X)\right\},
$$

and the exceptional set to be

$$
Y_{e}=Y \backslash\left(Y_{0} \cup Y_{1}\right)
$$

The following result is known as Holsztyński's Theorem ([11, 12]). We include a sketch of the proof here for completeness.

Lemma 2.2 (Holsztyński). There is a continuous surjective map $\varphi$ from $Y_{1}$ onto $X$ and $a$ unimodular scalar continuous function $h$ on $Y_{1}$ such that

$$
T f_{\mid Y_{1}}=h \cdot f \circ \varphi, \quad \forall f \in C_{0}(X)
$$

In other words, $T f(y)=h(y) f(\varphi(y))$ for all $y$ in $Y_{1}$.
Sketch of the proof. Let $F=\operatorname{ran} T$ be the (necessarily closed) range space of the isometry $T$. The dual map $T^{*}: M(Y) \longrightarrow M(X)$ induces an affine homeomorphism $\Phi$ from the closed dual ball $F_{1}^{*}$ of $F$ onto $M_{1}(X)$ in weak* topologies. In particular, $\Phi$ maps ext $F_{1}^{*}$ onto ext $M_{1}(X)$. Hence, for each $x$ in $X$ there is an extreme point $\eta$ in $F_{1}^{*}$ of norm one such that $\Phi(\eta)=\delta_{x}$. Since the set of all norm one extensions of $\eta$ to $C_{0}(X)$ is a nonempty weak* closed face of $M_{1}(Y)$, there is a (not necessarily unique) extreme point $\frac{\delta_{y}}{\lambda}$ in ext $M_{1}(Y)$ such that $T^{*}\left(\frac{\delta_{y}}{\lambda}\right)=\delta_{x}$, or $T^{*} \delta_{y}=\lambda \delta_{x}$. In particular, $y \in Y_{1}$. Set $\varphi(y)=x$ and $h(y)=\lambda$ whenever $T^{*}\left(\delta_{y}\right)=\lambda \delta_{x}$. It is then routine to verify that $\varphi$ and $h$ are well-defined and continuous on $Y_{1}$ such that $\varphi\left(Y_{1}\right)=X,|h(y)|=1$ on $Y_{1}$, and $T f_{\mid Y_{1}}=h \cdot f \circ \varphi$ for all $f$ in $C_{0}(X)$.

We remark that $\varphi(y)=x$ if and only if $|T f(y)|=|f(x)|$ for all $f$ in $C_{0}(X)$, as the latter ensures $\operatorname{ker} T^{*} \delta_{y}=\operatorname{ker} \delta_{x}$.

Lemma 2.3. The set $Y_{0} \cup Y_{1}$ is closed in $Y$. Moreover, if we extend $\varphi$ by setting

$$
\varphi_{\mid Y_{0} \cup\{\infty\}} \equiv \infty
$$

then the surjective map $\varphi: Y_{0} \cup Y_{1} \cup\{\infty\} \longrightarrow X \cup\{\infty\}$ is again continuous.
Proof. Let $\left\{y_{\lambda}\right\}_{\lambda}$ be a net in $Y_{0} \cup Y_{1}$ such that $y_{\lambda} \rightarrow y$ for some $y$ in $Y$. We want to verify that $y \in Y_{0} \cup Y_{1}$. Suppose $y$ does not belong to the closed set $Y_{0}=\bigcap\left\{(T f)^{-1}\{0\}: f \in C_{0}(X)\right\}$, we can then assume that $y_{\lambda}$ is in $Y_{1}$ for all $\lambda$. Let $x_{\lambda}=\varphi\left(y_{\lambda}\right) \in X$. We have

$$
\begin{equation*}
\left|f\left(x_{\lambda}\right)\right|=\left|T f\left(y_{\lambda}\right)\right| \rightarrow|T f(y)|, \quad \forall f \in C_{0}(X) . \tag{1}
\end{equation*}
$$

Note that there is some $f$ in $C_{0}(X)$ with $T f(y) \neq 0$ since $y \notin Y_{0}$. Let $x$ be any cluster point of the net $\left\{x_{\lambda}\right\}_{\lambda}$ in $X \cup\{\infty\}$. By (1), we have $x \neq \infty$ and

$$
|T f(y)|=|f(x)|, \quad \forall f \in C_{0}(X)
$$

Hence, $y \in Y_{1}$ and $\varphi(y)=x$. Thus, $Y_{0} \cup Y_{1}$ is closed in $Y$.
To verify the continuity of $\varphi$, we show that $\varphi\left(y_{\lambda}\right) \rightarrow \varphi(y)$ in $X \cup\{\infty\}$ whenever $y_{\lambda} \rightarrow y$ in $Y_{0} \cup Y_{1} \cup\{\infty\}$. By first half of the proof, it suffices to check that $\varphi\left(y_{\lambda}\right) \rightarrow \infty$ whenever $y \in Y_{0} \cup\{\infty\}$. Indeed, this follows from the observation

$$
0=|T f(y)|=\lim _{\lambda}\left|T f\left(y_{\lambda}\right)\right|=\lim _{\lambda}\left|f\left(\varphi\left(y_{\lambda}\right)\right)\right|, \quad \forall f \in C_{0}(X) .
$$

Note that as an open subset of a closed subset of a locally compact space, $Y_{1}$ is locally compact of its own.

Lemma 2.4. Let $T_{1}: C_{0}(X) \longrightarrow C_{0}\left(Y_{1}\right)$ be the linear isometry defined by $T_{1} f=T f_{\mid Y_{1}}$ for all $f$ in $C_{0}(X)$. Then

$$
\operatorname{ran} T_{1}=\left\{g \in C_{0}\left(Y_{1}\right): \frac{g(a)}{h(a)}=\frac{g(b)}{h(b)} \text { whenever } a, b \in Y_{1} \text { such that } \varphi(a)=\varphi(b)\right\}
$$

Proof. One inclusion is plain since $T_{1} f=h \cdot f \circ \varphi$. Suppose $g$ in $C_{0}\left(Y_{1}\right)$ satisfies that $\frac{g(a)}{h(a)}=\frac{g(b)}{h(b)}$ whenever $\varphi(a)=\varphi(b)$. Define a function $f$ on $X$ by

$$
f(x)=\frac{g(y)}{h(y)} \quad \text { if } y \in Y_{1} \text { and } \varphi(y)=x
$$

Since $\varphi\left(Y_{1}\right)=X$ (Lemma 2.2), such an $f$ is well-defined on $X$. To see $f$ is continuous, we assume on the contrary that $x_{\lambda} \rightarrow x$ in $X \cup\{\infty\}$ but $\left|f(x)-f\left(x_{\lambda}\right)\right|>\epsilon$ for some $\epsilon>0$. Let $x_{\lambda}=\varphi\left(y_{\lambda}\right)$ for some $y_{\lambda}$ in $Y_{1}$. Let $y$ be a cluster point of $\left\{y_{\lambda}\right\}_{\lambda}$ in $Y_{0} \cup Y_{1} \cup\{\infty\}$. By Lemma 2.3, $\varphi(y)$ is a cluster point of $\left\{x_{\lambda}\right\}_{\lambda}$. Thus $\varphi(y)=x$. If $x \in X$ then $y \in Y_{1}$ and $\frac{g(y)}{h(y)}=f(x)$ is a cluster point of $f\left(x_{\lambda}\right)=\frac{g\left(y_{\lambda}\right)}{h\left(y_{\lambda}\right)}$, a contradiction. In case $x_{\lambda} \rightarrow \infty$, we see that $y \in Y_{0} \cup\{\infty\}$ by Lemma 2.3. Since $h$ is unimodular, we have $\left|f\left(x_{\lambda}\right)\right|=\left|g\left(y_{\lambda}\right)\right| \rightarrow 0$, a contradiction again. Therefore, $f \in C_{0}(X)$ and $g=T f \in \operatorname{ran} T_{1}$.

From now on, we assume that $T: C_{0}(X) \longrightarrow C_{0}(Y)$ is a linear isometry with finite corank $n$. Let $\# A$ denote the cardinality of a set $A$.

Definition 2.5. Let

$$
M=\left\{y \in Y_{1}: \varphi^{-1}\{\varphi(y)\} \text { contains at least two points }\right\}
$$

be the set of merging points, $\varphi(M)$ the set of merged points and the number $\# M-\# \varphi(M)$ the merging index of $T$. Call also the number $\# Y_{0}$ the vanishing index and $\# Y_{e}$ the exception index of $T$.

## Lemma 2.6.

$$
\# M-\# \varphi(M) \leq n
$$

and

$$
\# Y_{0}+\# Y_{e} \leq n
$$

Proof. It follows from Lemma 2.4 that $\# M-\# \varphi(M)=\operatorname{corank} T_{1} \leq \operatorname{corank} T=n$. For the second inequality, we note that $Y_{e}=Y \backslash Y_{0} \cup Y_{1}$ is open in $Y$ by Lemma 2.3. Suppose there are distinct $p_{1}, \ldots, p_{k}$ in $Y_{0}$ and $y_{1}, \ldots, y_{l}$ in $Y_{e}$. Then we can choose $f_{1}, \ldots, f_{k}, g_{1}, \ldots, g_{l}$ in $C_{0}(Y)$ with mutually disjoint supports such that

$$
f_{1}\left(p_{1}\right)=\cdots=f_{k}\left(p_{k}\right)=g_{1}\left(y_{1}\right)=\cdots=g_{l}\left(y_{l}\right)=1
$$

and

$$
g_{j \mid Y_{0} \cup Y_{1}} \equiv 0, \quad j=1, \ldots, l
$$

We claim that these $k+l$ functions are linear independent modulo the range space of $T$. To this end, let

$$
T f=\lambda_{1} f_{1}+\cdots+\lambda_{k} f_{k}+\alpha_{1} g_{1}+\cdots+\alpha_{l} g_{l}
$$

for some $f$ in $C_{0}(X)$ and scalars $\lambda_{1}, \ldots, \lambda_{k}, \alpha_{1}, \ldots, \alpha_{l}$. By evaluating at each $p_{i}$, we get $\lambda_{i}=0$ for $i=1, \ldots, k$. It then follows $T f_{\mid Y_{0} \cup Y_{1}} \equiv 0$ and, in particular, $|f(\varphi(y))|=$ $|T f(y)|=\left|\sum_{j=1}^{l} \alpha_{j} g_{j}(y)\right|=0$ for all $y$ in $Y_{1}$. Since $\varphi\left(Y_{1}\right)=X$, we have $f=0$. This makes $\alpha_{1}=\cdots=\alpha_{l}=0$ since $g_{1}, \ldots, g_{l}$ have disjoint supports. As a result, $l+k \leq \operatorname{corank} T=$ $n$.

Corollary 2.7. 1. Both the vanishing set $Y_{0}$ and the exceptional set $Y_{e}$ are finite.
2. $Y_{e}$ consists of isolated points in $Y$.
3. Suppose $X$ is compact. Then both $Y$ and $Y_{1}$ are compact and $Y_{0}$ consists of isolated points in $Y$.

Proof. We mention that $Y_{e}$ is an open set by Lemma 2.3. In case $X$ is compact, $\infty$ is isolated in $X \cup\{\infty\}$ and Lemma 2.3 ensures $Y_{0} \cup\{\infty\}=\varphi^{-1}\{\infty\}$ is also open. The assertions follow since finite open sets consists of isolated points.

The following example borrowed from [13] says that $Y_{0}$ can contain non-isolated point if $X$ is not compact.

Example 2.8 ([13]). Let $X$ be the disjoint union in $\mathbb{R}^{2}$ of $I_{n}^{+}=\{(n, t): 0<t \leq 1\}$ and $I_{n}^{-}=\{(n, t):-1<t<0\}$ for $n=1,2, \ldots$ Let $p$ be the point $(1,1)$ and let $X_{1}=X \backslash\{p\}$. Let $\varphi$ be the homeomorphism from $X_{1}$ onto $X$ by sending the intervals $I_{1}^{+} \backslash\{p\}$ onto $I_{1}^{-}$, $I_{n+1}^{+}$onto $I_{n}^{+}$, and $I_{n}^{-}$onto $I_{n+1}^{-}$in a canonical way for $n=1,2, \ldots$ Then the corank one linear isometry $T f=f \circ \varphi$ from $C_{0}(X)$ into $C_{0}(X)$ has exactly one vanishing point, i.e., $p$. We note that $p$ is not an isolated point in $X$. In a similar manner, one can even construct an example in which $X$ is connected (by adjoining each $I_{n}^{ \pm}$a common base point, for example).

Theorem 2.9. The map $\varphi:\left(Y_{1}, M\right) \longrightarrow(X, \varphi(M))$ is a relative homeomorphism. More precisely, $\varphi: Y_{1} \backslash M \rightarrow X \backslash \varphi(M)$ is a homeomorphism, and the induced map $\widetilde{\varphi}: Y_{1} \sim X$ is also a homeomorphism, where " $\sim$ " is the equivalence relation such that $y_{1} \sim y_{2}$ if and only if $\varphi\left(y_{1}\right)=\varphi\left(y_{2}\right)$.

Proof. It suffices to show that $y_{\lambda} \rightarrow y$ in $Y_{1}$ whenever $\varphi\left(y_{\lambda}\right) \rightarrow \varphi(y)$ in $X$. Suppose $y^{\prime}$ is any cluster point of $\left\{y_{\lambda}\right\}$ in $Y_{0} \cup Y_{1} \cup\{\infty\}$ which is compact by Corollary 2.7. It follows from Lemma 2.3 that $\varphi\left(y^{\prime}\right)$ is a cluster point of $\left\{\varphi\left(y_{\lambda}\right)\right\}$. Thus $\varphi(y)=\varphi\left(y^{\prime}\right)$ and, in particular, $y^{\prime} \in Y_{1}$. If $y$ is not a merging point, i.e. $y \notin M$, then $y=y^{\prime}$. In case $y$ is a merging point, the above argument tells us that the equivalence class $[y]=\varphi^{-1}\{\varphi(y)\}$ contains all cluster points $y^{\prime}$ of $\left\{y_{\lambda}\right\}$. This shows that the induced map $\widetilde{\varphi}$ is also a homeomorphism.

Lemma 2.10. Fix each $y^{\prime}$ in $Y_{e}$, there is a $\mu^{\prime}$ in $M(Y)$ supported by $Y_{1}$ such that

$$
g\left(y^{\prime}\right)=\int_{Y_{1}} \frac{g(y)}{h(y)} d \mu^{\prime}(y), \quad \forall g \in \operatorname{ran} T
$$

Proof. Let $\nu=\delta_{y^{\prime}} \circ T \in M(X)$. If $\nu(x)=0$ for all $x$ in $\varphi(M)$, then we can set $\mu^{\prime}(\{y\})=0$ for all $y$ in $M$ and $\mu^{\prime}(B)=\nu\left(\varphi\left(B \cap Y_{1}\right)\right.$ ) for all Borel subsets $B$ of $Y$ disjoint from $M$. It follows from Theorem 2.9 that $\mu^{\prime} \in M(Y)$. Clearly, $\mu^{\prime}$ satisfies the stated condition. In case $\nu(\{x\}) \neq 0$ for some merged point $x$ in $\varphi(M)$ and $\varphi^{-1}\{x\}=\left\{y_{1}, \ldots, y_{k}\right\}$, we may set $\mu^{\prime}\left(\left\{y_{1}\right\}\right)=\cdots=\mu^{\prime}\left(\left\{y_{k}\right\}\right)=\nu(\{x\}) / k$. Since $\frac{g\left(y_{1}\right)}{h\left(y_{1}\right)}=\cdots=\frac{g\left(y_{k}\right)}{h\left(y_{k}\right)}=f(x)$ if $T f=g$, we again have the stated condition.

Theorem 2.11. The sum of the vanishing, exception and merging indices of a corank $n$ linear isometry $T: C_{0}(X) \longrightarrow C_{0}(Y)$ is $n$. In other words,

$$
\# Y_{0}+\# Y_{e}+\# M-\# \varphi(M)=n
$$

In fact,

$$
\begin{aligned}
\operatorname{ran} T=\left\{g \in C_{0}(X): g_{\mid Y_{0}} \equiv 0, \quad g\left(y^{\prime}\right)=\int_{Y_{1}} \frac{g(y)}{h(y)} d \mu^{\prime}(y) \text { for all } y^{\prime} \text { in } Y_{e}\right. \\
\text { and } \left.\frac{g(a)}{h(a)}=\frac{g(b)}{h(b)} \text { whenever } a, b \in M \text { such that } \varphi(a)=\varphi(b)\right\}
\end{aligned}
$$

where $T f_{\mid Y_{1}}=h \cdot f \circ \varphi$ and $\mu^{\prime}$ is the Borel measure in $M(Y)$ associated to each $y^{\prime}$ in $Y_{e}$ as in Lemmas 2.2 and 2.10.

Proof. From Lemmas 2.2, 2.4 and 2.10, we have already had one side inclusion. For the other inclusion, we suppose a $g$ in $C_{0}(Y)$ satisfies all $\# Y_{0}+\# Y_{e}+\# M-\# \varphi(M)$ linear independent conditions stated on the right hand side. Set

$$
f(x)=\frac{g(y)}{h(y)} \quad \text { whenever } y \in Y_{1} \text { and } \varphi(y)=x
$$

By the proof of Lemma 2.4, we have $f \in C_{0}(X)$ and $T f$ agrees with $g$ on $Y_{1}$. It is plain that $T f$ also agrees with $g$ on $Y_{0}$ and

$$
T f\left(y^{\prime}\right)=\int_{Y_{1}} \frac{T f(y)}{h(y)} d \mu^{\prime}(y)=\int_{Y_{1}} f(\varphi(y)) d \mu^{\prime}(y)=\int_{Y_{1}} \frac{g(y)}{h(y)} d \mu^{\prime}(y)=g\left(y^{\prime}\right), \quad \forall y^{\prime} \in Y_{e}
$$

Hence $g=T f$, and consequently, $\# Y_{0}+\# Y_{e}+\# M-\# \varphi(M)=n$.
Remark 2.12. (a) In the recent literature, corank 1 linear isometries are of particular interests. In [1], corank 1 linear isometries of function algebras are classified into three types. Recall that a subset of $C_{0}(Y)$ is said to separate points in $Y$ (resp. $Y_{\infty}$ ) strongly if for any distinct $y$ and $y^{\prime}$ in $Y$ (resp. $Y_{\infty}$ ) there is a $g$ in this subset such that $|g(y)| \neq\left|g\left(y^{\prime}\right)\right|$. In [1], a corank 1 linear isometry $T: A \longrightarrow B$ between function algebras is said to be of
Type I: if the range of $T$ separates points in $Y$ strongly, except for two of them.
Type II: if the range of $T$ separates points in $Y$, but not in $Y_{\infty}$, strongly.
Type III: if the range of $T$ separates points in $Y_{\infty}$ strongly.
In case $A=C_{0}(X)$ and $B=C_{0}(Y)$, our structure theory (Theorem 2.11) simply says that $T$ is of Type I, II, or III if and only if either the merging, the vanishing, or the exception index of $T$ is 1 . Our approach seems to be more convenient in the higher dimensional case (cf. [7]).
(b) By Corollary 2.7, $Y_{e}$ consists of isolated points. Consequently, if $Y$ is connected then every corank 1 linear isometry $T$ from $C_{0}(X)$ into $C_{0}(Y)$ must be of Type I or Type II. In general, $T$ is of Type I or Type II if and only if $T$ is disjointness preserving, i.e. $f g=0$ implies $T f T g=0$. Hence, we may also divide linear isometries of finite corank into two classes: ones preserve disjointness and the others do not.
(c) If $X$ is compact then $Y_{0}$ consists of isolated points by Corollary 2.7. However, if $X$ is not compact then $Y_{0}$ can contain non-isolated points as shown in Example 2.8. This example provides us more insights into a result in [1, Theorem 6.1], which deals with the preservation of Shilov boundaries of function algebras by a corank 1 linear isometry.

## 3. IsOMETRIC (QUASI-) $n$-SHIFTS ON $C_{0}(X)$

Recall that an isometric quasi- $n$-shift $T$ on $C_{0}(X)$ is a corank $n$ linear isometry from $C_{0}(X)$ into itself. All results in Section 2 thus apply. In particular, we have the following generalization of [8, Theorem 2.6].

Proposition 3.1. Let $X$ be a compact Hausdorff space with at most finitely many isolated points. If $C(X)$ admits an isometric quasi-n-shift $T$, then there is a finite subset $M$ of $X$ and a relative homeomorphism $\varphi:(X, M) \longrightarrow(X, \varphi(M))$ such that $n=\#(M)-\#(\varphi(M))$. Moreover, the induced quotient $\operatorname{map} \widetilde{\varphi}: X / \sim \rightarrow X$ is a homeomorphism, where $\sim$ is the equivalence relation on $X$ such that $x \sim x^{\prime}$ if and only if $\varphi(x)=\varphi\left(x^{\prime}\right)$.

Proof. By Lemma 2.2, Tf $=h \cdot f \circ \varphi$ for a continuous unimodular scalar function $h$ on $X$ and a surjective continuous map $\varphi$ from $X_{1}$ onto $X$. By Corollary 2.7, both $X_{0}$ and $X_{e}$ are empty since $X$ is compact and contains at most finitely many isolated points; for else the set $\left\{\varphi^{-n}\{x\}: n=1,2, \ldots\right\}$ would contain infinitely many isolated points in $X$ for any $x$ in $X_{0} \cup X_{e}$. Hence, $X=X_{1}$. The assertions now follow from Theorem 2.9.

Corollary 3.2. Let $X$ be a path-connected compact Hausdorff space in which points are strong deformation retract of compact neighborhoods. If $C(X)$ admits an isometric quasi-$n$-shift then the first homological group $H_{1}(X)$ of $X$ has infinitely many free generators.

Proof. Suppose $x \in \varphi(M)$ and $\varphi^{-1}\{x\}=\left\{y_{1}, \ldots, y_{l}\right\}$. Consider the long exact sequence:

$$
\begin{aligned}
\cdots \rightarrow H_{1}\left(\left\{y_{1}, \ldots, y_{l}\right\}\right) \rightarrow H_{1}(X) & \rightarrow H_{1}\left(X,\left\{y_{1}, \ldots, y_{l}\right\}\right) \\
& \rightarrow H_{0}\left(\left\{y_{1}, \ldots, y_{l}\right\}\right) \rightarrow H_{0}(X) \rightarrow H_{0}\left(X,\left\{y_{1}, \ldots, y_{l}\right\}\right)
\end{aligned}
$$

Since $X$ is path-connected and points are strong deformation retract of compact neighborhoods in $X$, the above long exact sequence gives a short exact sequence

$$
0 \rightarrow H_{1}(X) \rightarrow H_{1}\left(X / \sim_{x}\right) \rightarrow \mathbb{Z}^{l-1} \rightarrow 0
$$

where $\sim_{x}$ is the equivalence relation defined on $X$ by identifying $y_{1}, \ldots, y_{l}$. Hence,

$$
H_{1}\left(X / \sim_{x}\right) \cong H_{1}(X) \oplus \mathbb{Z}^{l-1}
$$

Let $x^{\prime}$ be another point in $\varphi(M)$ and $\varphi^{-1}\left\{x^{\prime}\right\}=\left\{y_{1}^{\prime}, \ldots, y_{k}^{\prime}\right\}$. Applying the same argument to $X / \sim_{x}$, we get

$$
H_{1}\left(X / \sim_{x, x^{\prime}}\right) \cong H_{1}\left(X / \sim_{x}\right) \oplus \mathbb{Z}^{k-1} \cong H_{1}(X) \oplus \mathbb{Z}^{l+k-2},
$$

where $\sim_{x, x^{\prime}}$ is the equivalence relation defined on $X$ by identifying $y_{1}, \ldots, y_{l}$ and identifying $y_{1}^{\prime}, \ldots, y_{k}^{\prime}$. In this manner, we would get

$$
H_{1}(X / \sim) \cong H_{1}(X) \oplus \mathbb{Z}^{n}
$$

since $n=\# M-\# \varphi(M)$, where $\sim$ is the equivalent relation defined as in Proposition 3.1. Because $X / \sim$ and $X$ are homeomorphic, the assertion follows.

We note that the first homological group of any finite-dimensional compact topological manifold is finitely generated (see e.g. [17, p. 163]). Suggested by [8, Corollary 2.4], we extend [6, Theorem 6.1] in the following

Corollary 3.3. There is no finite-dimensional compact topological manifold $X$ such that $C(X)$ admits any isometric quasi-n-shift.

Remark 3.4. In a similar manner, results in [3] can be applied so that Corollaries 3.2 and 3.3 are also valid for disjointness preserving quasi- $n$-shifts.

Let $T$ be an isometric quasi- $n$-shift on $C_{0}(X)$ such that $T f=h \cdot f \circ \varphi$ on $X_{1}$ (Lemma 2.2). In the following, we discuss the structure of the range spaces of the powers $T^{k}$ of $T$. For convenience, we extend $h$ to $X_{\infty}$ be setting $h \equiv 1$ on $X_{\infty} \backslash X_{1}$. Note that $h$ is not necessarily continuous unless $X$ is compact (Corollary 2.7).

Let $X_{e}=\left\{q_{1}, \ldots, q_{m}\right\}$ be the exceptional set of $T$. For each $q$ in $X_{e}$, let $\mu$ be the bounded regular Borel measure in $M(X)$ supported by $X_{1}$ defined as in Lemma 2.10 such that

$$
T f(q)=\int_{X_{1}} \frac{T f(y)}{h(y)} d \mu(y), \quad \forall f \in C_{0}(X) .
$$

In a similar manner, we can construct a sequence $\left\{\mu_{k}\right\}$ of bounded regular Borel measures in $M(X)$ supported by $X_{1}$ such that $T^{*}\left(\frac{\mu_{k+1}}{h}\right)=\mu_{k}$ for $k=0,1, \ldots$. Here we set $\mu_{0}=T^{*} \delta_{q}$ and $\mu_{1}=\mu$. In general, let $\mu_{k+1}(B)=\mu_{k}\left(\varphi\left(B \cap X_{1}\right)\right)$ for all Borel subsets $B$ of $X$ disjoint from the merging set $M$, and for each merged point $x$ in $\varphi(M)$ we let $\mu_{k+1}\left(\left\{y_{1}\right\}\right)=\cdots=$ $\mu_{k+1}\left(\left\{y_{k}\right\}\right)=\mu_{k}(\{x\}) / k$ if $\varphi^{-1}\{x\}=\left\{y_{1}, \ldots, y_{k}\right\}$. Moreover, we identify points $x$ in $X$ with point evaluations $\delta_{x}$ in $M(X)$, and $\infty$ with the zero measure.

Definition 3.5. A $T$-branch originated at a point $x$ in $X_{\infty}$ is defined to be the set

$$
B_{x}=\bigcup\left\{\varphi^{-n}(x): n=0,1,2, \ldots\right\}
$$

where $\varphi^{0}(x)=\{x\}$ and $\varphi^{-n}(x)=\left\{y \in X: \varphi^{n}(y)=x\right\}$ for $n=1,2, \ldots$. We note that $x=\varphi(y)$ if and only if $T^{*}\left(\frac{\delta_{y}}{h}\right)=\delta_{x}$. Suppose $\mu$ is the bounded Borel measure in $M(X)$ associated simultaneously to $q_{1}, q_{2}, \ldots, q_{r}$ in $X_{e}$, i.e. $T^{*} \delta_{q_{i}}=\mu$ for $i=1,2, \ldots, r$. We define the $T$-branch $B_{\mu}$ originated at $\mu$ to be the union of the sequence $\left\{\mu_{k}\right\}$ and $B_{q_{i}}$ for $i=1,2, \ldots, r$. The $T$-tree is a directed graph, whose vertex set is the union of all $T$ branches $B_{x}$ originated at some point $x$ in $\varphi(M)$ (and also at $x=\infty$ if $Y_{0} \neq \emptyset$ ) and all
$T$-branches $B_{\mu}$ originated at some $\mu$ associated to a point $q$ in $X_{e}$. There is a directed edge from $\mu$ to $\nu$ if and only if $T^{*}(\mu / h)=\nu$. In case $\mu$ and $\nu$ are point masses at $y$ and $x$ in $X_{\infty}$ respectively, we will write $x \leftarrow y$ instead. Note that this is equivalent to $\varphi(y)=x$.

The branch of the $T$-tree originated at $\mu$ may look like:


This $T$-branch has at least $r$ "joints" (and maybe more "joints" at some subsequent vertex $\left.\varphi^{-1}\left(q_{j}\right)\right)$. In general, the whole $T$-tree has exactly $n$ "joints" if $T$ is a quasi- $n$-shift.

Example 3.6. Let $\ell_{\infty}$ be the Banach space of bounded scalar sequences. We can identify $\ell_{\infty}$ as $C(\beta \mathbb{N})$, where $\beta \mathbb{N}$ is the Stone-Cech compactification of the natural numbers $\mathbb{N}$. Define an isometric shift $T$ on $\ell_{\infty}$ be $T\left(x_{1}, x_{2}, \ldots\right)=\left(0, x_{1}, x_{2}, \ldots\right)$. The $T$-tree is


Note that the $T$-tree is dense in $X=\beta \mathbb{N}$.
Example 3.7. Let $c_{0}=C_{0}(\mathbb{N})$ be the Banach space of null sequences. Let $T: c_{0} \rightarrow c_{0}$ be defined by

$$
T\left(\left(x_{1}, x_{2}, x_{3}, \ldots\right)\right)=\left(x_{1},-\frac{x_{1}+x_{2}}{2}, x_{2}, x_{3}, \ldots\right)
$$

Then $T$ is an isometric quasi-shift on $c_{0}$. In this case, $X=\mathbb{N}, X_{0}=\emptyset, X_{e}=\{2\}$, $X_{1}=\mathbb{N} \backslash\{2\}, h \equiv 1$ on $\mathbb{N} \backslash\{2\}$, and $\varphi: \mathbb{N} \backslash\{2\} \rightarrow \mathbb{N}$ is a homeomorphism defined by $\varphi(1)=1$ and $\varphi(n+1)=n$ for $n=2,3, \ldots$ Moreover, we have $M=\varphi(M)=\emptyset$ and

$$
\mu=T^{*} \delta_{2}=-\frac{\delta_{1}+\delta_{2}}{2}
$$

where $\delta_{m}$ is the point evaluation at $m$ in $\mathbb{N}$. The $T$-tree is

where

$$
\begin{aligned}
& \mu_{1}=\mu \circ \varphi=-\frac{\delta_{\varphi^{-1}(1)}+\delta_{\varphi^{-1}(2)}}{2}=-\frac{\delta_{1}+\delta_{3}}{2} \\
& \mu_{2}=\mu \circ \varphi^{2}=-\frac{\delta_{\varphi^{-2}(1)}+\delta_{\varphi^{-2}(2)}}{2}=-\frac{\delta_{1}+\delta_{4}}{2}
\end{aligned}
$$

and, in general, for $m=1,2, \ldots$,

$$
\mu_{m}=\mu \circ \varphi^{m}=-\frac{\delta_{\varphi^{-m}(1)}+\delta_{\varphi^{-m}(2)}}{2}=-\frac{\delta_{1}+\delta_{m+2}}{2}
$$

We verify that $T$ is a shift on $c_{0}$, i.e., $\bigcap_{m=1}^{\infty} \operatorname{ran} T^{m}=\{0\}$. It follows from Theorem 2.11 that the range space of $T$ is

$$
\operatorname{ran} T=\left\{g=\left(g_{m}\right)_{m=1}^{\infty} \in c_{0}: g_{2}=-\frac{g_{1}+g_{3}}{2}\right\}
$$

It is also easy to see that

$$
\begin{aligned}
& T^{2} f(3)=T f(\varphi(3))=T f(2)=\int f(x) d \mu(x) \\
& \quad=\int f(\varphi(y)) d \mu(\varphi(y))=\int T f(y) d \mu_{1}(y)=\int T f(\varphi(z)) d \mu_{1}(\varphi(z))=\int T^{2} f(z) d \mu_{2}(z)
\end{aligned}
$$

for all $f$ in $c_{0}$. Hence,

$$
\operatorname{ran} T^{2}=\left\{g=\left(g_{m}\right)_{m=1}^{\infty} \in c_{0}: g_{2}=-\frac{g_{1}+g_{3}}{2} \text { and } g_{3}=-\frac{g_{1}+g_{4}}{2}\right\}
$$

In this manner, for any $g=\left(g_{m}\right)$ in $c_{0}$, we have

$$
\begin{aligned}
g \in \bigcap_{m=1}^{\infty} \operatorname{ran} T^{m} & \Leftrightarrow g(m+1)=\int g d \mu_{m}, \quad \forall m=1,2, \ldots \\
& \Leftrightarrow g_{m+1}=-\frac{g_{1}+g_{m+2}}{2}, \quad \forall m=1,2, \ldots \\
& \Leftrightarrow g_{1}=-2 g_{m+1}-g_{m+2}, \quad \forall m=1,2, \ldots
\end{aligned}
$$

As a result, $g_{1}=0$ and thus

$$
2 g_{m+1}+g_{m+2}=0, \quad \forall m=1,2, \ldots
$$

Consequently,

$$
\left|g_{m+1}\right|=\frac{\left|g_{m+2}\right|}{2}=\frac{\left|g_{m+3}\right|}{2^{2}}=\cdots=\frac{\left|g_{m+k}\right|}{2^{k}} \rightarrow 0, \quad \text { as } k \rightarrow \infty
$$

Hence, $g=0$, and thus $\bigcap_{m=1}^{\infty} \operatorname{ran} T^{m}=\{0\}$.

Suppose $T$ is an isometric quasi- $n$-shift on $C_{0}(X)$ and $T f=h \cdot f \circ \varphi$ on $X_{1}$. Denote by

$$
h \circ \varphi_{k!}(x)=h(x) h(\varphi(x)) \cdots h\left(\varphi^{k-1}(x)\right), \quad \forall x \in X_{\infty}, \forall k=1,2, \ldots
$$

We set $h_{\mid X_{\infty} \backslash X_{1}}=1$ for convenience.
Definition 3.8. A $g$ in $C_{0}(X)$ is said to be $h$-equipotential on the $T$-tree at level $k$ if we have

$$
\int \frac{g}{h \circ \varphi_{k!}} d \mu_{k}=\int \frac{g}{h \circ \varphi_{k!}} d \nu_{k}
$$

whenever the two vertices $\mu_{k}$ and $\nu_{k}$ in the $T$-tree are connected forward by $k$ directed edges to the same vertex. Note that points $x$ in $X$ are identified with point masses $\delta_{x}$ in $M(X)$.

The following result is obtained by the same argument given in Example 3.7.

Proposition 3.9. Let $T$ be an isometric quasi-n-shift on $C_{0}(X)$. The range space of the power $T^{m}$ is given by

$$
\operatorname{ran} T^{m}=\left\{g \in C_{0}(X): g \text { is } h \text {-equipotential on the } T \text {-tree at levels } 1,2, \ldots, m\right\}
$$

Corollary 3.10. The $T$-tree is weak* total in $M(X)$ whenever $T$ is an isometric $n$-shift on $C_{0}(X)$.

We remark that the converse of Corollary 3.10 is not true. For example, consider the isometric quasi-shift $T\left(x_{1}, x_{2}, x_{3}, \ldots\right)=\left(x_{1}, x_{1}, x_{2}, x_{3}, \ldots\right)$ on $c=C(\mathbb{N} \cup\{\infty\})$. The $T$-tree

$$
\bigcirc_{1<\quad} 1<\quad 3<\ldots .
$$

is dense in $X=\mathbb{N} \cup\{\infty\}$ although $T$ is not a shift.
Example 3.11. Let

$$
X=\{1,2,3, \ldots, \infty, \infty+1, \infty+2, \ldots, \infty+l\}
$$

be the disjoint union of $\mathbb{N}_{\infty}=\mathbb{N} \cup\{\infty\}$ and a discrete set of $l$ points. Let $T: C(X) \rightarrow C(X)$ be the isometric shift defined by

$$
\begin{aligned}
& T\left(\left(x_{1}, x_{2}, x_{3}, \ldots, x_{\infty}, x_{\infty+1}, \ldots, x_{\infty+l-1}, x_{\infty+l}\right)\right) \\
& \quad=\left(x_{\infty+1}, x_{1}, x_{2}, \ldots, x_{\infty}, x_{\infty+2}, \ldots, x_{\infty+l},-x_{\infty+1}\right)
\end{aligned}
$$

Then $T f=h \cdot f \circ \varphi$ for all $f$ in $C(X)$. Here, $h(\infty+l)=-1$ and $h \equiv 1$ elsewhere. The relative homeomorphism $\varphi:(X,\{1, \infty+l\}) \longrightarrow(X,\{\infty+1\})$ is represented by the following $T$-tree, which is the branch originated at the merged point $\infty+1$. Here, $a \leftarrow b$ indicates $\varphi(b)=a$. Moreover, $\varphi(\infty)=\infty$.


We verify that $\cap_{m=1}^{\infty} \operatorname{ran} T^{m}=\emptyset$. By Proposition 3.9,

$$
\begin{gathered}
\operatorname{ran} T=\{g \in C(X): g(1)=-g(\infty+l)\} \\
\operatorname{ran} T^{2}=\{g \in C(X): g(1)=-g(\infty+l), g(2)=-g(\infty+l-1)\}
\end{gathered}
$$

In fact, a $g$ in $C(X)$ is $h$-equipotential on the $T$-tree at level $k$ if and only if

$$
\frac{g(k)}{h \circ \varphi_{k!}(k)}=\frac{g\left(\infty+l-k_{1}\right)}{h \circ \varphi_{k!}\left(\infty+l-k_{1}\right)},
$$

or

$$
g(k)=(-1)^{r} g\left(\infty+l-k_{1}\right),
$$

where $k=r l-k_{1}$ and $0 \leq k_{1}<l$. This makes $g(k)=0$ for $k=1,2, \ldots, \infty$. It then in turn forces $g(\infty+k)=0$ for $k=1,2, \ldots, l$. Hence, $g=0$ as asserted.

Note that the $T$-tree has exactly one joint at $\infty+1$, and it is dense in $X$. In fact, only the limit point $\infty$ is missing from the $T$-tree above.

Remark 3.12. In [8] and [6], the authors considered the notion of types. Example 3.11 was used in [6] to show that there is a type I isometric 1 -shift $T$ such that $T$ is a weighted composition operator on $X \backslash\{q\}$ and the set

$$
D=\left\{q, \varphi^{-1}(q), \varphi^{-2}(q), \ldots\right\}
$$

is not dense in $X$. In this case, $q=1$ and $D=\mathbb{N}$. But we have seen above that the $T$-tree is dense in $X$, indeed. It seems to us that the notions of types of shifts and the set $D$ (and $F$ in their notations) can be misleading in some situations.

Note that the unilateral shift defined only on separable Hilbert spaces. The action of the unilateral shift can be thought of a shift on a countable orthonormal basis. Although it is now a basis free theory for isometric shifts $T$ on $C_{0}(X)$, the $T$-tree can be considered as a "basis" for the shift $T$. Corollary 3.10 says this countable "basis" is total in $M(X)$. Thus $M(X)$ is weak* separable. We are interested in knowing when $X$ is separable. Recall that a measure $\mu$ in $M(X)$ is separately supported if the $\operatorname{support} \operatorname{supp}(\mu)$ of $\mu$ is a separable subset of $X$.

Theorem 3.13. Suppose $C_{0}(X)$ admits an isometric $n$-shift T. If all measures $\mu^{\prime}=\delta_{y^{\prime}} \circ T$ arising from points $y^{\prime}$ in $X_{e}$ are separately supported then $X$ is separable.

Proof. We first note that the assumption implies all measures appearing in the $T$-tree are separately supported. In fact, every such measure is either a point mass or the one obtained by successively composing those $\mu^{\prime}$ with $\varphi$ in a finite steps. For the latter, the supports is separable since $\varphi:\left(X_{1}, M\right) \longrightarrow(X, \varphi(M))$ is a relative homeomorphism and $M$ is a finite set. Let $S$ be the countable union of the supports of all the measures appearing in the $T$-tree. Then $S$ has a countable dense subset. Finally, we claim $S$ is dense in $X$. It is plain that every $g$ in $C_{0}(X)$ vanishing on $S$ is zero at each vertex in the $T$-tree. By Corollary 3.9, all such $g$ are in the range of $T^{m}$ for $m=1,2, \ldots$. This forces $g$ being constantly zero since $T$ is an $n$-shift. Hence $S$ is dense in $X$, as asserted.

Corollary 3.14. Suppose $C_{0}(X)$ admits an isometric $n$-shift $T$. Then $X$ is separable if any one of the following holds.

1. $X$ does not contain infinitely many isolated points.
2. The range space of $T$ cannot strongly separate points in $X_{\infty}$ unless at least $n$ points are removed.
3. $T$ is disjointness preserving.
4. $X_{e}$ is empty.
5. The $T$-tree is contained in $X_{\infty}$.

Proof. It follows from the structure of the range space of $T$ (Theorem 2.11) that $T$ is disjointness preserving, if and only if, $X_{e}$ is empty, if and only if, the $T$-tree is contained in $X_{\infty}$. On the other hand, if $q$ is a point in $X_{e}$ then $q$ is isolated by Corollary 2.7. Consequently, the $T$-branch originated at $q$ consists of infinitely many isolated points in $X$. Hence the first condition also implies $X_{e}$ is empty. Finally, the second condition ensures that the merging index $\# M-\# \varphi(M)$ of $T$ is exactly $n$. Thus $X_{e}=\emptyset$ again. In all cases, Theorem 3.13 applies.

To end this paper, we remark that Araujo and Font [2] recently showed that if $X$ is a (not necessarily compact) metrizable space such that the Banach space $C_{b}(X)$ of bounded continuous functions on $X$ admits an isometric shift then $X$ is separable.

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